Electron-phonon interaction in embedded semiconductor nanostructures

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The modification of acoustic phonons in semiconductor nanostructures embedded in a host crystal is investigated including corrections due to strain within continuum elasticity theory. Effective elastic constants are calculated employing *ab initio* density functional theory. For a spherical InAs quantum dot embedded in GaAs as barrier material, the electron-phonon coupling is calculated. Its strength is shown to be suppressed compared to the assumption of bulk phonons.

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I. INTRODUCTION

Semiconductor nanostructures have attracted increasing interest over the last couple of years. Especially quantum dots (QD) are proposed as possible candidates in applications such as single photon sources and quantum information devices. Improved growth techniques nowadays enable the fabrication of small QDs with a narrow size distribution. Single, isolated QDs embedded in a semiconductor matrix or in solution are of high interest for basic research. Since their electronic properties are inevitably connected to the underlying lattice and its vibrations (phonons) they offer the possibility to study these fundamental interactions. While the theory for electron-phonon interaction in bulk systems is well established, the inhomogeneous nature of nanostructures leads to strong modifications of the electronic properties as well as the phonon spectrum.^{1,2} The existence of boundaries between the constituting materials and/or to the vacuum introduces a coupling of the longitudinal and transverse phonon modes even for isotropic media. Additionally, new types of confined interface and surfaces modes can occur

The electron-acoustic phonon interaction is of high interest since it is the source of so-called pure dephasing of optical excitations in QDs, as detailed in recent articles.^{3,4} The interaction is usually treated by deformation potential coupling, and acoustic phonons are described as bulk phonons. Only recently some progress has been made to include phonons in inhomogeneous media in the treatment of electron-phonon interaction in slab and half space geometries.³

The present article provides insights into the role of the phonon modification due to the nanostructure, including strain. We restrict ourselves to the simplest case—a spherical QD—in order to describe the qualitative effect on the electron-acoustic phonon coupling. The details of the model and the corresponding theory are developed in Sec. II. Calculations of strain dependent acoustic phonons on the basis of *ab initio* density functional theory (DFT) calculations are given in Sec. II B which serve as input for the calculation of the electron-phonon coupling function. Results are given in Sec. III.

II. MODEL AND THEORY

Epitaxial growth methods enable the fabrication of semiconductor heterostructures with sizes of a few nanometers only. The different materials are connected pseudomorphically, i.e., without structural defects. Defects would lead to partial relaxation of intrinsic strain which results from different lattice constants of the constituents. The strain itself causes the change of physical properties compared to relaxed bulk materials. This includes the electronic (band structure) as well as the lattice properties (phonons).

The system we study in this article is a spherical shape inclusion (quantum dot) in an infinite matrix (barrier). This artificial system should serve as test model for the relevance of nonbulk phonon modes in the electron-phonon coupling. For the material parameters we choose the prototype InAs/GaAs system. The first part is devoted to the description of the acoustic phonons within continuum elasticity theory followed by the description of the electron-acoustic phonon coupling.

A. Acoustic phonons within continuum elasticity

In continuum elasticity theory, acoustic phonons follow from the wave equation of the displacement field u(r) (Ref. 5)

$$-\omega^2 \rho(\mathbf{r}) u_j(\mathbf{r}) = \sum_k \frac{\partial}{\partial x_k} \sigma_{jk}(\mathbf{r}), \qquad (1)$$

here written in Cartesian coordinates j,k=x,y,z. Both the mass density $\rho(\mathbf{r})$ and the stress tensor $\vec{\sigma}(\mathbf{r})$ are in general spatially dependent. In linear elasticity theory the stress tensor $\vec{\sigma}$ is proportional to the strain tensor $\vec{\epsilon}$ defined by the spatial derivatives of the displacement fields, both quantities being related by the fourth order tensor of elastic constants \vec{C} (Hooke's law). For isotropic systems there are only two independent elastic constants C_{11} and C_{44} , which are related to the well-known Lamé coefficients $C_{12}=C_{11}-2C_{44}=\lambda$ and $C_{44}=\mu$. The stress tensor elements are then given by

$$\sigma_{jk} = \delta_{jk} (C_{11} - 2C_{44}) \sum_{l} \frac{\partial u_l}{\partial x_l} + C_{44} \left(\frac{\partial u_j}{\partial x_k} + \frac{\partial u_k}{\partial x_j} \right).$$
(2)

The restriction to isotropic media allows to treat the phonons in large part analytically.

For our spherical model system it is convenient to transform to spherical coordinates. For the specific electronphonon coupling considered below, the only relevant phonon mode has angular momentum zero (breathing mode) $\mathbf{u}(\mathbf{r}) = \mathbf{e}_r u(r)$, which fulfills the equation

$$0 = \rho(r)\omega^2 u(r) - 4 \frac{dC_{44}(r)}{dr} \frac{u(r)}{r} + \frac{d}{dr} \left[C_{11}(r) \left(\frac{du(r)}{dr} + \frac{2u(r)}{r} \right) \right]$$
(3)

with elastic constants and mass density having an arbitrary radial dependence. This one-dimensional second-order differential equation contains the boundary conditions for a stepwise constant medium as well, which are

$$u$$
 and $C_{11}\left(\frac{du}{dr} + \frac{2u}{r}\right) - 4C_{44}\frac{u}{r}$ continuous. (4)

The general normalization condition of the displacement within a large volume Ω reads⁶

$$\int_{\Omega} d^3 r \rho(\mathbf{r}) \mathbf{u}_{\nu}(\mathbf{r}) \cdot \mathbf{u}_{\nu'}(\mathbf{r}) = \delta_{\nu,\nu'} \frac{\hbar}{2\omega_{\nu}}, \qquad (5)$$

where ν is the discrete mode index. This normalization is converted into a matching condition at large distances with an outgoing wave containing a phase shift, as standard in scattering theory. Details are discussed in the Appendix. As a consequence, ν is replaced by a (continuous) energy variable $\hbar \omega_{\nu} \rightarrow E$.

The elastic constants in Eq. (3) are not to be taken as the usual tabulated bulk values for the dot and the barrier material: The phonon calculation has to start from the reference state where the crystal is locally under finite strain. Therefore the spatial dependency is not only due to the change in material but also due to the spatially varying strain.

B. Effective elastic constants from DFT

The usual treatment of continuum elasticity assumes fixed elastic constants. In our case, however, the system contains spatial regions where the material is strained. This leads to an effective change of the local elastic constants. The numerical values can be taken for homogeneously strained bulk systems assuming that the elastic constants depend only on the local strain, i.e., $\mathbf{C}(\mathbf{r}) = \mathbf{C}(\mathbf{\vec{\epsilon}}(\mathbf{r}))$. The calculation of elastic constants for periodic systems is possible directly by employing ab initio density functional theory (DFT). Within perturbation theory a single calculation is sufficient to get the full fourth order tensor of elastic constants for a specific deformation of the unit cell. The DFT calculations are carried out with the ABINIT computer code.^{7–9} The local density approximation (LDA) is applied for the exchange-correlation energy. Soft norm-conserving pseudopotentials are taken from the code of the Fritz-Haber Institute, Berlin.¹⁰ Wave functions are expanded into plane waves with converged Monkhorst-Pack meshes of $k=8\times8\times8$ per unit cell and a cutoff energy of E_{cut} =36 Ha=979 eV.

Intuitively, one would expect that a homogeneous material under compression would become harder due to the presence of anharmonic terms in the expansion of the free energy density around the equilibrium position (reference state),



FIG. 1. (Color online) Effective elastic constants for GaAs (black) and InAs (red) in dependence on the lattice constant a for hydrostatic deformations calculated by DFT employing perturbation theory. The (experimental) equilibrium lattice constants are marked by full vertical lines, while the lattice constant of the relaxed InAs QD is given by the dashed line.

$$\rho_0 \phi = \frac{1}{2} \sum_{I,J} C_{IJ} \epsilon_I \epsilon_J + \frac{1}{3!} \sum_{I,J,K} C_{IJK} \epsilon_I \epsilon_J \epsilon_K + \cdots$$
 (6)

Here, capital indices refer to Voigt's notation⁵ ($I=1\cdots 6$) of the strain tensor $\vec{\epsilon}$ with components ϵ_I and the elastic constants. The C_{IJ} are the components of the \vec{C} fourth order tensor and describe linear elasticity completely. C_{IJK} give anharmonic contributions still in the homogeneous system. The equilibrium density is written as ρ_0 . We restrict ourselves to hydrostatic compressions in the following. An extension to general deformations is straightforward but numerically a far more complex task. Allowing only small distortions of the lattice (an expansion up to second order is sufficient), only the bulk modulus $B=1/3(C_{11}+2C_{12})$ would be a constant quantity. Including terms up to third order an analytical derivation gives a linear dependence on the strength of the hydrostatic lattice distortion.¹¹

The dependence of the calculated elastic constants on the (variable) lattice constant, which corresponds to hydrostatic deformation, is displayed in Fig. 1. In the range from -7 to +7 % lattice constant variation we find a nearly linear reduction of C_{11} and C_{12} with increasing the lattice constant, which is expected from a third order expansion,¹¹ showing that even for small distortions the assumption of constant elasticity does not hold. The deviation from the linear behavior, especially for C_{44} , is a clear indication that even higher orders than the third one influence significantly the effective elastic constants. Numerical deviations from the experimental values are mainly due to the known underestimation of the lattice constant in LDA for III-V semiconductors (see Table I). Given a local static lattice distortion, it is now possible to implement these elastic constants in the phonon calculation, which depend on the spatial position due to change in material and strain as well.

C. Electron-acoustic phonon coupling

The electron-acoustic phonon interaction has two main contributions: Deformation potential coupling and piezoelec-

TABLE I. Parameters used in the calculation for the unstrained material (Ref. 14). Given are also the theoretical lattice constants a_0 (DFT). Last row: Resulting values for the embedded strained InAs quantum dot (s-InAs).

	m_e $[m_0]$	D_C [eV]	CBO [meV]	ρ [g/cm ³]	<i>a</i> ₀ (exp.) [Å]	a ₀ (DFT) [Å]
GaAs	0.067	-7.17	0	5.33	5.65	5.51
InAs	0.026	-5.08	-894	5.66	6.06	6.05
s-InAs	0.026	-5.08	-208	6.50	5.79	

tric coupling. The second contribution will not be considered here, although some of the following discussions apply also to this part.

For conduction electrons at the Γ -point in III-V semiconductors the deformation potential couples only to a volume deformation (div **u**). The interaction Hamiltonian is⁶

$$H_{\rm def}(\mathbf{r}) = \sum_{\nu} D_C(\mathbf{r}) [b_{\nu}^{\dagger} \operatorname{div} \mathbf{u}_{\nu}(\mathbf{r}) + \text{H.c.}]$$
(7)

with the (material-dependent) deformation potential constant for the conduction band D_C and the phonon creation operator b_{ν}^{\dagger} . In a QD with confinement functions $\varphi_n(\mathbf{r})$ of the electron, the relevant electron-phonon matrix elements are then

$$M_{\nu}^{nm} = \int d^3 r \varphi_n^*(\mathbf{r}) \varphi_m(\mathbf{r}) D_C(\mathbf{r}) \text{div } \mathbf{u}_{\nu}(\mathbf{r}).$$
(8)

The spherical symmetry of the QD leads to well-defined angular quantum numbers of the confinement levels, which select an appropriate symmetry of the lattice displacement. For electronic *s*-*s* transitions, only the azimuthal quantum number l=0 is needed (breathing mode). For the polaronic modification of a single electronic transition within the independent Boson model,¹² the diagonal element in Eq. (8) is of central importance. Concentrating on the lowest (*s*-type) confinement state n=1, we need to calculate the following coupling function:¹³

$$f(E) = \sum \delta(E - \hbar \omega_{\nu}) |M_{\nu}^{11}|^2.$$
 (9)

For instance, the so-called broad band around the zerophonon line at E=0 has a shape close to $f(E)/E^3$ at elevated temperatures (strictly speaking, the hole confinement state participating in the transition has to be included as well).

III. RESULTS AND DISCUSSION

In the following we present results for a spherical QD consisting of pure InAs embedded in infinitely extended GaAs. First, the strain distribution has to be determined which then serves as input for the effective spatial dependent elastic constants to be used in Eq. (3). Under hydrostatic compression the coordinates change according to $x'_j = (1 - \alpha)x_j$. The deformation α can be determined from the static solution (ω =0) of Eq. (3). Applying the boundary conditions from Eq. (4) accordingly leads to

$$\alpha = \alpha_0 \frac{C_{44,\text{GaAs}}}{C_{44,\text{InAs}} - C_{44,\text{GaAs}} + \frac{3}{4}C_{11,\text{InAs}}}$$
(10)

with the lattice mismatch α_0 . For the present InAs/GaAs model system, it is $\alpha_0 = (a_{0,\text{InAs}} - a_{0,\text{GaAs}})/a_{0,\text{InAs}} = 6.8\%$ using the experimental values given in Table I. The relaxed lattice constant *a* of the dot material (InAs), which is compressed hydrostatically, is therefore $a_{\text{InAs}} = a_{0,\text{InAs}}(1-\alpha)$ (last row of Table I, and indicated in Fig. 1 as dashed line.) Outside the dot, the material is compressed in radial direction but dilated laterally resulting in a zero net volume change. Since we consider only hydrostatic compression the elastic properties are taken unchanged for the barrier material.

Having all the input for Eq. (3) it can be solved numerically. In the common approximation of using bulk phonons (here of the barrier material—index B), the solution gives simply $u_E^{(B)}(r) = j_1(k_B r)$ with $j_l(x)$ being the spherical Bessel function of the first kind (see also the Appendix). The wave number is related to the energy via $E = \hbar v_{IB} k_B (v_l = \sqrt{C_{11}/\rho}$ is the longitudinal sound velocity).

For the full problem, the displacement inside the dot (index D) starts as $u_E(r)=A(E)j_1(k_Dr)$ for $r \rightarrow 0$. After solving Eq. (3) numerically, the prefactor A(E) has to be determined by matching with the outgoing wave solution

$$u_E(r \to \infty) = -\cos(k_B r - \delta_E)/(k_B r) \tag{11}$$

according to the asymptotics of the spherical Besssel function. If the material parameters change steplike in radial direction at the dot-barrier interface an analytic solution is possible, which is discussed in the Appendix. Our numerical solution agrees exactly in this case with the analytic treatment, but more general problems of continuously changing elastic properties can be calculated. Although the integration in the matrix element extends into the barrier material, it is mainly the variation of A(E) which modifies the coupling function. In order to implement the change in wave number (sound velocity) as well, we found it convenient to define a phonon amplitude as

$$P(E) = A(E) \frac{v_{lB}}{v_{lD}}.$$
 (12)

By definition, for bulk barrier phonons, $P(E) \equiv 1$ which is the normalization used in Fig. 2.

Whereas for a free standing sphere as well as for a rigidly clamped sphere, only discrete phonon energies are allowed, the QD embedded in an *infinite* elastic medium allows for a continuous manifold of phonon energies. However, the oscillating behavior of the phonon amplitude shown in Fig. 2 resembles the eigenmodes of an isolated sphere. A specific feature is the reduction of the phonon amplitude at small energies: Including the strain, its overall strength is reduced even further. Doubling the size of the embedded dot from R=5 nm to R=10 nm leads to halve the energetic spacing between maxima, while the overall amplitude remains the same. This can be understood by noting that within the applied approximation, neither the static strain field nor the material density depends on the size of the QD.



FIG. 2. (Color online) Energy dependence of the phonon amplitudes for an InAs sphere of radius R embedded into GaAs material. The unrealistic situation without strain is compared with the strained one.

The last step is to insert the phonon modes $u_E(r)$ into the electron-phonon matrix element Eq. (8). The calculation of the electron confinement wave function is done within the effective mass approximation including mass discontinuities

$$\left(-\frac{\hbar^2}{2}\nabla\frac{1}{m_e(\mathbf{r})}\nabla - V(\mathbf{r})\right)\varphi_n(\mathbf{r}) = \varepsilon_n\varphi_n(\mathbf{r}).$$
(13)

Inserting the ground state electron $\varphi_1(r)$ (radially symmetric) and phonon functions $u_E(r)$ into Eq. (8) gives for the electron-phonon coupling Eq. (9) the result

$$f(E) = \frac{4E}{\hbar\rho_B v_{lB}^3} \left| \int_0^\infty dr \varphi_1^2(r) D_C(r) \frac{d}{dr} r^2 u_E(r) \right|^2.$$
(14)

If the phonon modes are approximated by bulk ones of the barrier, the resulting coupling function is

$$f^{(B)}(E) = \frac{4E^3 D_{CB}^2}{\hbar^3 \rho_B v_{lB}^5} \left| \int_0^\infty dr r^2 \varphi_1^2(r) j_0(k_B r) \right|^2.$$
(15)

Divided by E^3 it follows the (squared) Fourier transform of the electron charge density, which decays on a scale of $E \approx \hbar v_{IB}/R$ (*R* is the QD radius).

All input variables are taken from existing literature¹⁴ and given in Table I. The compressive strain in the InAs dot reduces the conduction band offset (CBO) significantly. The resulting electron confinement potential is plotted in the in-



FIG. 3. (Color online) Electron-acoustic phonon coupling function. Compared are (a) the unstrained combination of an InAs QD (R=5 nm) embedded in GaAs and the more realistic (b) strained situation. In each panel the assumption of bulk phonons, either GaAs or InAs, is compared to the full phonon calculation. The inset shows the electron confinement potential and the corresponding charge density $r^2 \varphi_1^2(r)$.



FIG. 4. Electron-acoustic phonon coupling function: Compared are two different radii of the strained InAs QD embedded in GaAs.

sets of Fig. 3 together with the charge density in the lowest confinement state $r^2 \varphi_1^2(r)$. In the strained case [Fig. 3(b)], a larger tunneling of the wave function into the barrier can be seen. Surprisingly, in the present case, this change in the electronic wave function affects the electron-phonon coupling only marginal. This can be seen by comparing the electron-phonon coupling functions for GaAs bulk in Figs. 3(a) and 3(b) which differ only in the electronic wave function part.

The coupling function of electrons with acoustic phonons Eq. (14) is shown in Fig. 3 comparing the strain free case (a) with the improved description including the strain present in the nanostructure (b). Within each panel the approximation of bulk phonons using either barrier (GaAs) or dot (InAs) material parameter are displayed, too. Compared to "dotbulk phonons," a strong reduction is found, whereas "barrierbulk phonons" are much closer to the full solution, although missing the existing structure in the coupling function.

The compressive strain results in an increased mass density (see Table I), increased elastic constants in the dot and to a reduction of the coupling strength div $\mathbf{u}(\mathbf{r})$. The shape of the coupling function, mainly determined by the structure in the phonon amplitude, however, is not much changed when including strain. The coupling is reduced further by increasing the size of the QD, see Fig. 4. Here, the coupling function is even more structured (sharp drop at around 1 meV) which has its origin in the oscillatory variation of the phonon amplitude P(E) discussed before.

IV. CONCLUSIONS

Including the details of the phonon characteristics in semiconductor nanostructures is essential for a quantitative description of the electron-acoustic phonon coupling. Material parameters, i.e., mass density and elastic constants, are changed due to intrinsic strain in pseudomorphically grown heterostructures and are therefore spatially dependent. Within continuum elasticity this can be treated by introducing effective material parameters. There is a continuous energy spectrum for phonons of nanostructures embedded in an infinite elastic medium. Compared to the assumption of bulk phonons, an overall reduction of the electron-acoustic phonon coupling is found due to the structurally modified phonons, which are influenced by the strain in the nanostructure also. Resonancelike features in the phonon modes lead to changes in the line shape of the energy dependent coupling function which are more pronounced for midsize dots than for small dots.

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APPENDIX: ANALYTIC SOLUTION

For steplike elastic material properties an analytic solution of Eq. (3) is possible. In the present case, we have two regions, which are the dot (index *D*) for $r \le R$ and the barrier material r > R (index *B*). Introducing a phase shift δ into the standard spherical Bessel functions

$$j_{1,\delta}(x) = \frac{\sin(x-\delta)}{x^2} - \frac{\cos(x-\delta)}{x},$$
 (A1)

the solution of Eq. (3) can be expressed as

$$u_E(r) = \begin{cases} A(E)j_{1,0}(k_D r), & r \le R, \\ j_{1,\delta_E}(k_B r), & r > R \end{cases}$$
(A2)

and is in agreement with the outgoing wave condition Eq. (11). The original normalization Eq. (5) in a large sphere with radius R_{∞} would produce an additional factor

$$N = \sqrt{E/(4\pi\rho_B v_{lB}^2 R_\infty)} \tag{A3}$$

in Eq. (A2). The transition from Eq. (9) to Eq. (14) introduces the eigenvalue density

$$\frac{dE}{d\nu} = \frac{\hbar v_{lB}\pi}{R_{\infty}} \tag{A4}$$

in the denominator. The multiplication with N^2 removes the artificial dependence on R_{∞} and leads to the prefactor in Eq. (14) being linear in *E*.

Implementing the boundary conditions at the dot-barrier interface, Eq. (4), and introducing the abbreviations $x=k_DR$, $y=k_BR$, $t=\tan(x)$, and $T=\tan(y-\delta_E)$ the phase shift has to be extracted from

$$\frac{\kappa y^2}{1 - y/T} = \frac{x^2}{1 - x/t} + \eta$$
 (A5)

with $\kappa = C_{11}^B / C_{11}^D$ and $\eta = 4(C_{44}^B - C_{44}^D) / C_{11}^D$. The prefactor A(E) follows then from

$$A(E) = \frac{j_{1,\delta_E}(y)}{j_{1,0}(x)} = \sqrt{\frac{1+t^2}{1+T^2}} \frac{x - Tx/y}{y - ty/x}.$$
 (A6)

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